

# T/HIS 21.1

# T/HIS 21.1 – Contents

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# Workflows

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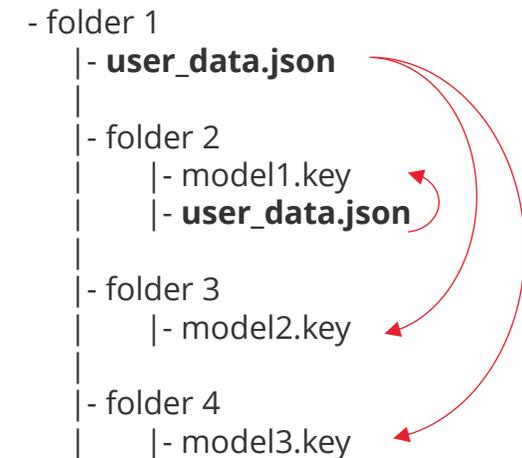
[Virtual Testing](#)

# Workflows User Data

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- We have made it easier for you to save Workflows user data to be re-used by multiple models and LS-DYNA runs.
- In Oasys 20, the JSON user data file written by a workflow tool had to be saved in the same folder as the model/results. This meant that if you had multiple variations of a model, you had to have copies of the same JSON file in each model/results folder, which was time consuming if edits needed to be made to the data.
- In Oasys 21, JSON user data can now also be saved in the parent folders of models, meaning the same data can be used for multiple models. The model folder is searched first, and then parent and grandparent folders are searched for valid JSON files. Preference **oasys\*workflow\_max\_upward\_folder\_search\_depth** can be set to control the number of parent folders that are searched. The default is 4.

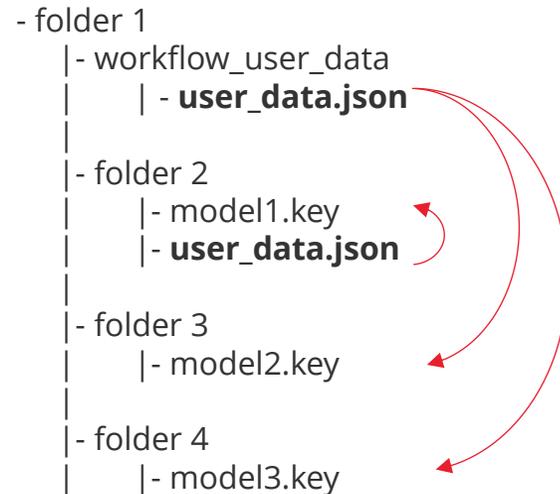
In this folder structure [right], the user\_data.json file in **folder 1** will be used for the models in folder 3 and folder 4, and the user\_data.json file in **folder 2** will be used for the model in folder 2:



# Workflows User Data

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- The scan will also look for user data in a folder named '**workflow\_user\_data**' in the model folder and its parent folders.
- For example, in the folder structure below, the user\_data.json file in **folder 1/workflow\_user\_data** will be used for the models in folder 3 and folder 4, and the user\_data.json file in **folder 2** will be used for the model in folder 2:



- The name of the folder to search can be changed by setting the preference **oasys\*workflow\_user\_data\_directory\_name**

# Automotive Assessments

In Oasys 21 the assessment values and scores are now presented in a table making it easier to view the results

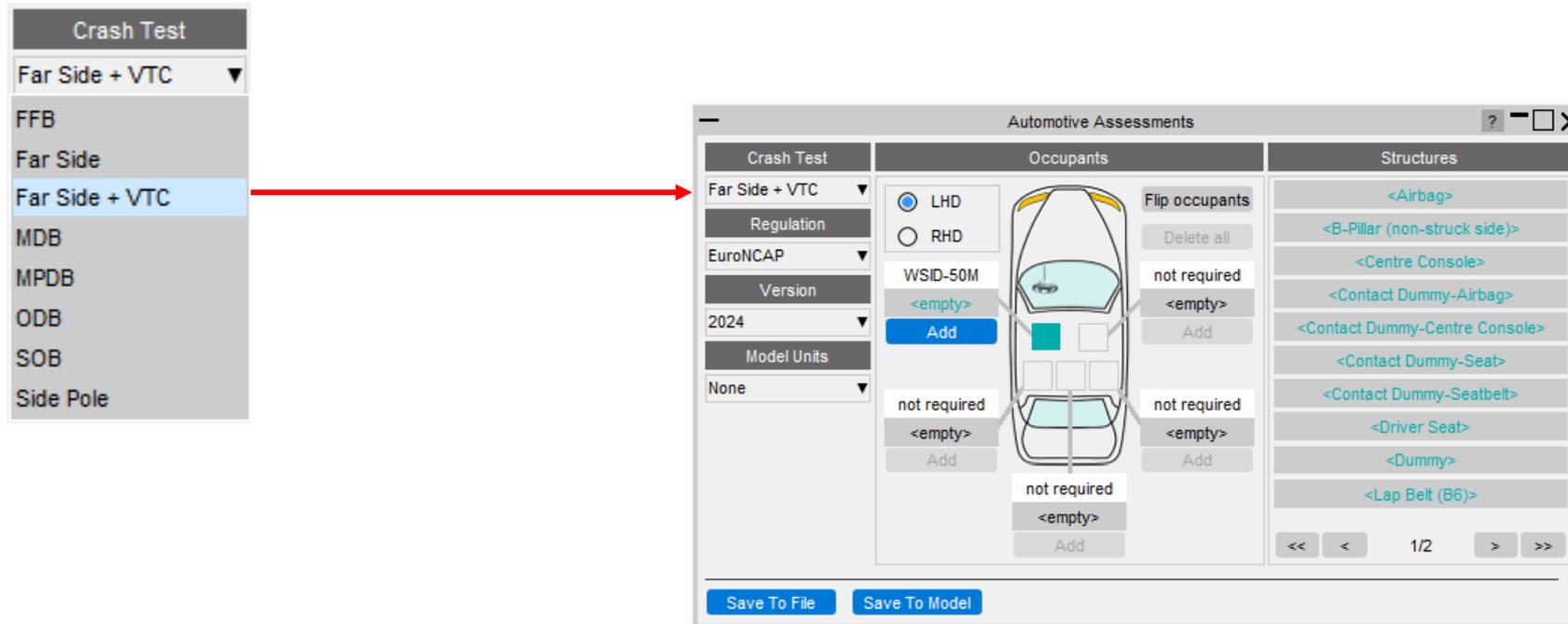
The screenshot displays the 'Automotive Workflow POST' software interface for a 'Crash Test: ODB'. The interface is divided into several sections:

- Regulation:** EuroNCAP, Rating Version: 2017, Unit Systems: M1 - U2 (mm, t, s).
- Occupants:** Driver, Front-passenger.
- Body Parts:** HEAD, NECK, CHEST, FEMUR, KNEE.
- Occupant Assessment Types:** LEFT\_KNEE\_COMPRESSION, RIGHT\_KNEE\_COMPRESSION.
- Structures:** A-Pillar, Accelerator Pedal, Brake Pedal, Clutch Pedal, Steering Column.
- Structure Assessment Types:** (Empty)
- Options:** Radio buttons for 'Graphs on same page' (selected), 'Graphs on separate pages', 'Overwrite existing graphs' (selected), and 'Append to existing graphs'.
- Buttons:** Plot, Import ISO-MME...
- Output Table:** A table with 8 columns: Tag, Location, Assessment Type, Parameter, Value, Duration, Score, and Curve. Two rows are visible, both for 'M1' at 'Front passenger'.

Tag	Location	Assessment Type	Parameter	Value	Duration	Score	Curve
M1	Front passenger	LEFT_KNEE_COMPRESSION	Max	6.50343 mm		3.776	->
M1	Front passenger	RIGHT_KNEE_COMPRESSION	Max	2.58155 mm		4.000	->

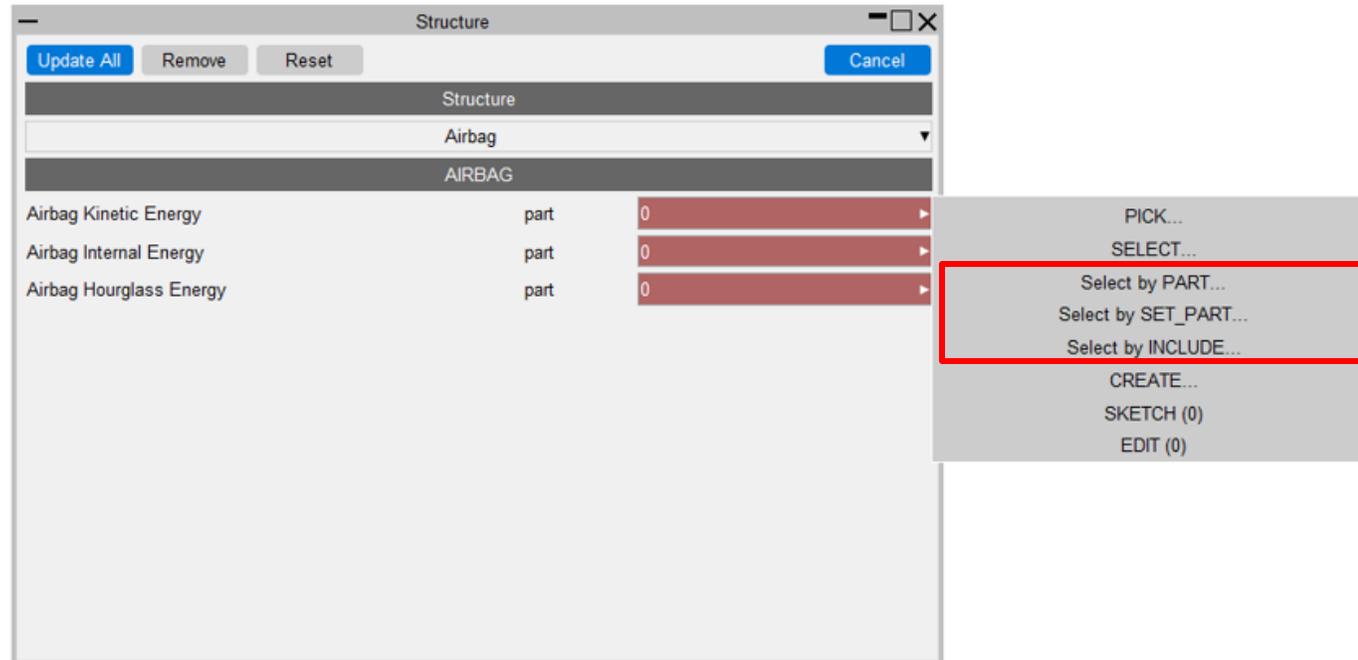
# Far Side + VTC crash test

- New **Far Side + VTC** crash test has been added in the Automotive Assessments workflow to support [Virtual Testing](#).
- Includes support for all 115 channels (Occupants + Structures) required for the [Euro NCAP Virtual Far Side Simulation & Assessment Protocol](#)



# Improved entity selection for multiple parts

- To facilitate multiple PARTs selection, new options have been added in the Automotive Assessments entity selection popup:
  1. Select by PART
  2. Select by SET\_PART
  3. Select by INCLUDE
- In the Far Side + VTC crash test, these options are useful for selecting multiple PARTs for structural channels like Kinetic Energy, Internal Energy, and Hourglass Energy, for Airbag, Centre Console, Driver Seat and Dummy.



# Updated support for different occupant versions

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- We now support the DYNAmore/PDB WorldSID 50M occupant in versions 4.0, 6.0, 7.6 and 8.0 for left-hand and right-hand drive.
- We have reviewed and corrected various entity IDs and history titles in occupant JSON files that are supported in Automotive Assessments workflow. The list of occupant JSON files and corresponding manual referenced for checking are listed in this [table](#).

# Euro NCAP Virtual Far Side Validation Criterion 2

- Automotive Assessments can be used to check Validation Criterion 2 manually, according to Section 6.3 of the [Euro NCAP Virtual Far Side Simulation & Assessment Protocol](#).
- Validation Criterion 2 check can also be automated using [Euro NCAP Virtual Far Side 2024 VC2 \(Assessment Criteria\) REPORTER](#) template .

Automotive Workflow POST

Crash Test: Far Side + VTC

Regulation: EuroNCAP, Rating Version: 2024, Unit Systems: M1 - U2 (mm, t, s), T1 - U1 (m, kg, s)

Occupants: (M1) Driver, (T1) Driver

Body Parts: HEAD, NECK, SHOULDER, CHEST, ABDOMEN

Occupant Assessment Types: HEAD\_HIC, HEAD\_THREE\_MS\_EXCEEDENCE, DRIVER\_HEAD\_EXCURSION

Structures: (M1) B-Pillar (non-struck side), (M1) Centre Console, (M1) Contact Dummy-Centre Console, (M1) Contact Dummy-Seat, (M1) Contact Dummy-Seatbelt

Structure Assessment Types

Options:  Graphs on same page,  Graphs on separate pages,  Overwrite existing graphs,  Append to existing graphs

Plot

Test Model: Import a test model: Import ISO-MME/CSV..., Select a test model: T1

Distance between head CoG and Orange line (mm): 770.34

Distance between head CoG and Red line (mm): 895.34

Countermeasure:

Tag	Location	Assessment Type	Parameter	Value	rAC Sim	rAC Test	dAC	Duration	Score	Curve
M1	Driver	DRIVER_HEAD_EXCURSION	Max	639.970 mm	0.811151	1.03511	0.223956		YELLOW	->
T1	Driver	DRIVER_HEAD_EXCURSION	Max	794.576 mm	N/A	1.03511	N/A		RED	->

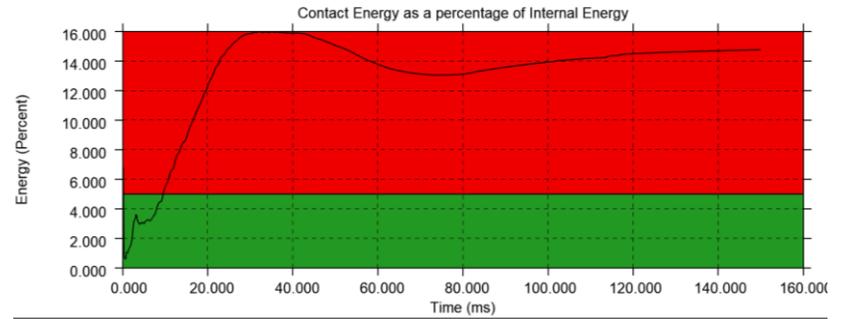
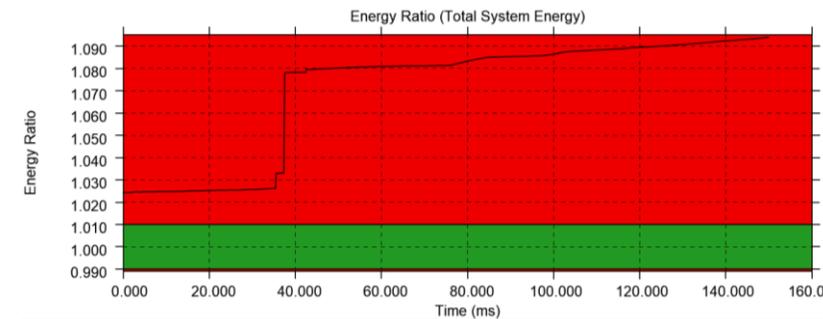
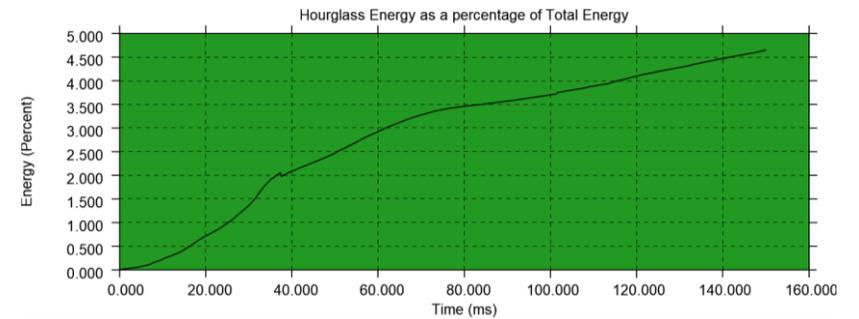
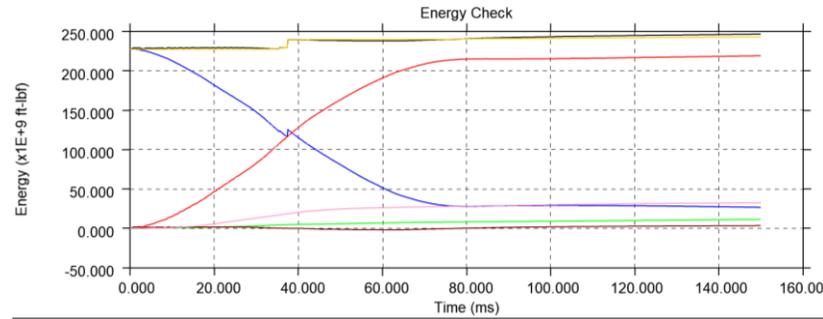
# New Protocols

- In Oasys 21.1, the following new protocols have been added to the Automotive Assessments workflow. Each of these represents a different loadcase required as part of the C-NCAP Management Regulation (2024 Edition).

Crash Test	Regulation	Version	Description
Far Side + VTC	C-NCAP	2024 (SID2-SBLD)	<ul style="list-style-type: none"> <li>Front passenger side impact, assessing driver (Far Side Occupant) injury.</li> <li>Injury scoring according to Chapter III section 1.2.1.5.3 of C-NCAP Management Regulation (2024 Edition) and Virtual Testing according to Appendix H.1.2.1.3.</li> </ul>
Far Side + VTC	C-NCAP	2024 (WSID)	
Far Side Pole	C-NCAP	2024 (ES-2re+WSID)	<ul style="list-style-type: none"> <li>Front passenger side impact, assessing driver (Far Side Occupant) injury according to Appendix H.1.2.2.2.</li> <li>Injury scoring based on Chapter III section 1.2.1.5.4 of C-NCAP Management Regulation (2024 Edition).</li> </ul>
Far Side Pole	C-NCAP	2024 (WSID+WSID)	
Side Pole	C-NCAP	2024 (WSID+ES-2re)	<ul style="list-style-type: none"> <li>Driver side impact assessing driver injury according to Appendix D.</li> <li>Injury scoring based on Chapter III section 1.2.1.4 of C-NCAP Management Regulation (2024 Edition).</li> </ul>
Side Pole	C-NCAP	2024 (WSID+WSID)	

# Energy Check

- Previously, the Energy Check tool simply plotted total, kinetic, internal and hourglass energy for your model. In Oasys 21, the tool now plots more energies, produces visual checks, and more.



Energy Check

Hourglass Energy is within your tolerance of Total Energy ✔

Absolute Total Contact Energy has hit a maximum of 15.99% of Internal Energy. This exceeds your tolerance of 5% ✘

Energy Ratio (Total System Energy) has increased to 1.09. This exceeds your tolerance of 1% ✘

Model Units U6 (m, t, s) Hourglass Energy Warning 5 %

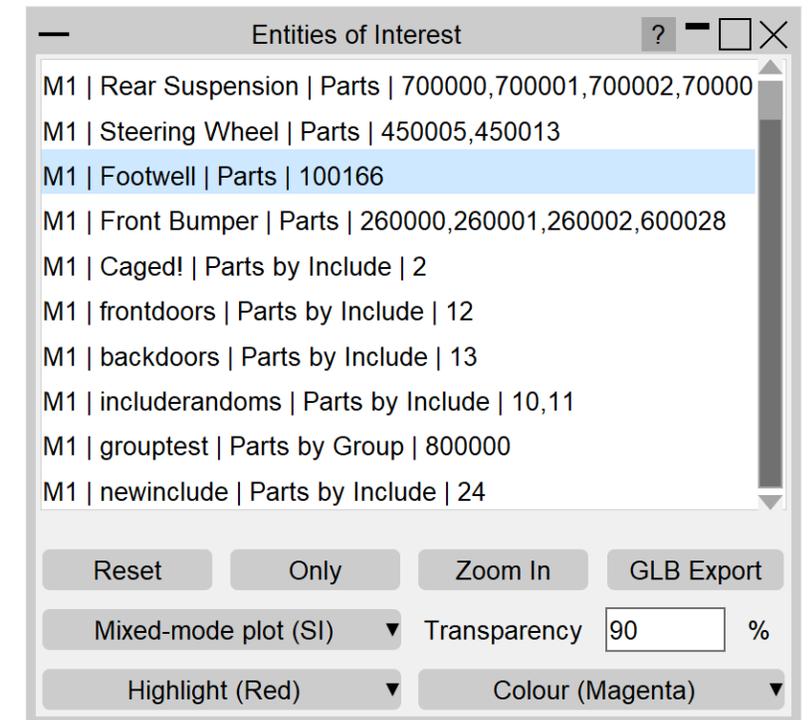
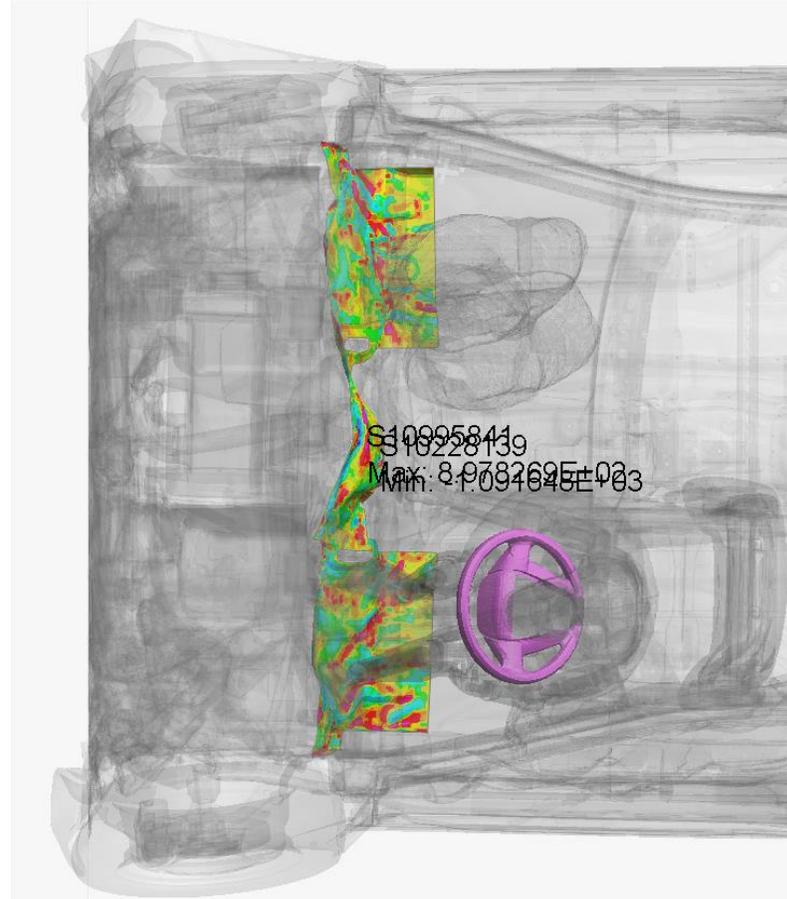
Display Time Units Milliseconds [ms] Contact Energy Warning 5 %

Display Energy Units Foot-Pounds [ft-lbf] Energy Ratio Tolerance 1 % Recalculate

Plot Parts with Greatest Total Energy (Max 6) 6 Plot Parts

# Entities of Interest

- Previously, the Entities of Interest tool was able to Only, Highlight and complete GLB Exports for selected entities grouped by Parts or Part Sets. In Oasys 21, you can now Zoom In, Colour By and produce Mixed-Mode Plots grouped by Parts, Parts by Set, Parts by Include and Parts by Group.



The image shown is an SI Mixed-Mode Plot on the Footwell and Coloured by Magenta on the Steering Wheel

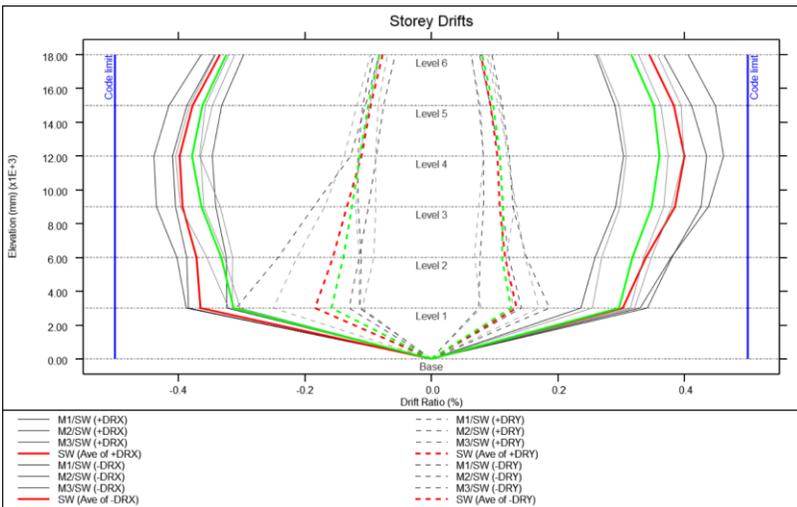
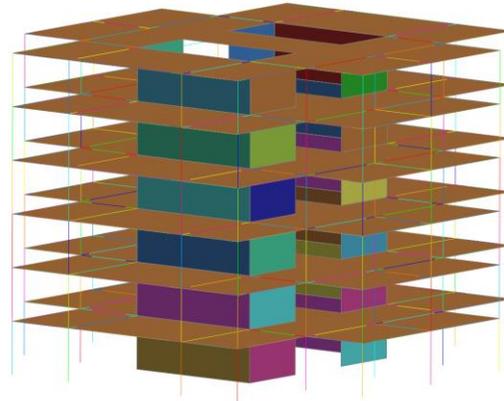
# Seismic Workflows

Oasys 21 features new tools to power two of the most common seismic analysis workflows:

## Storey Drift

In PRIMER, define drift nodes at different locations, for each storey.

In T/HIS, storey drifts are plotted for each location defined.

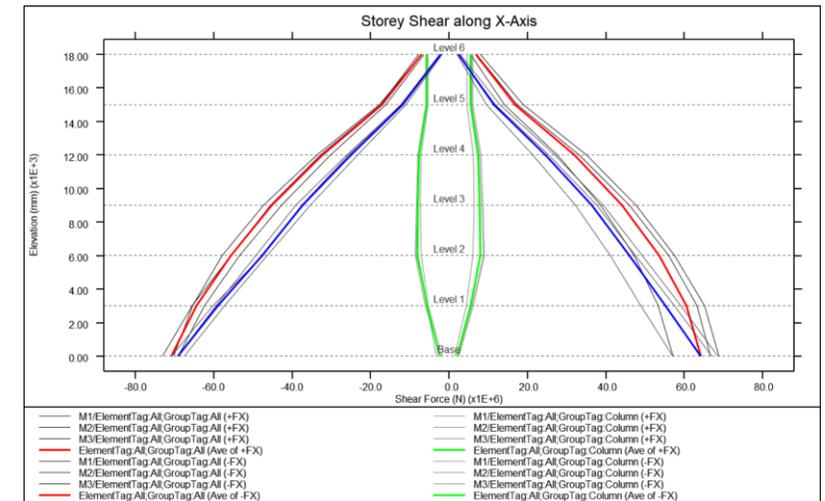


The Workflows can process a single model or a sweep of LS-DYNA runs for a set of ground motions.

## Storey Force

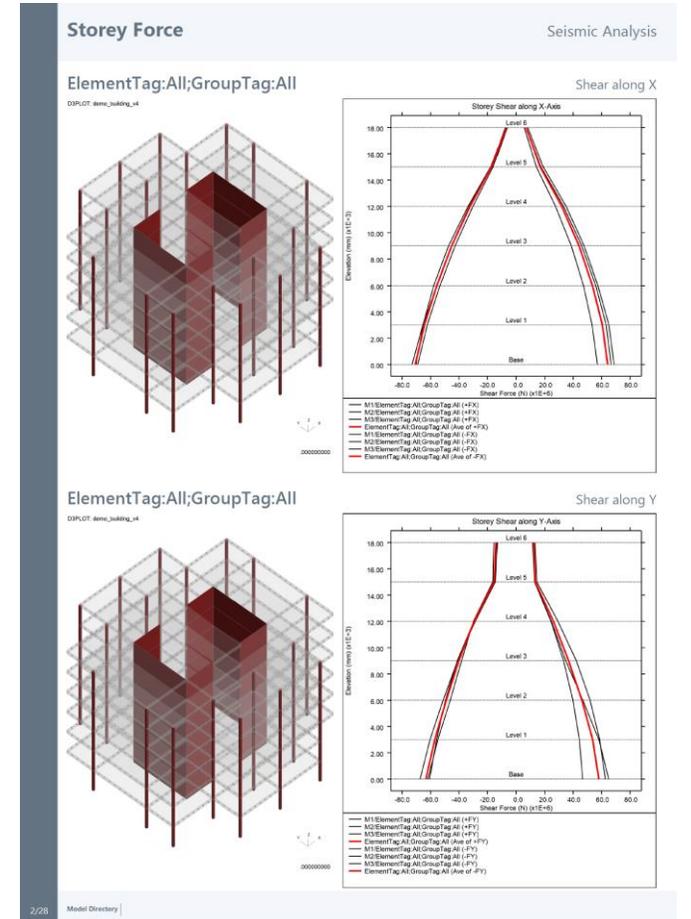
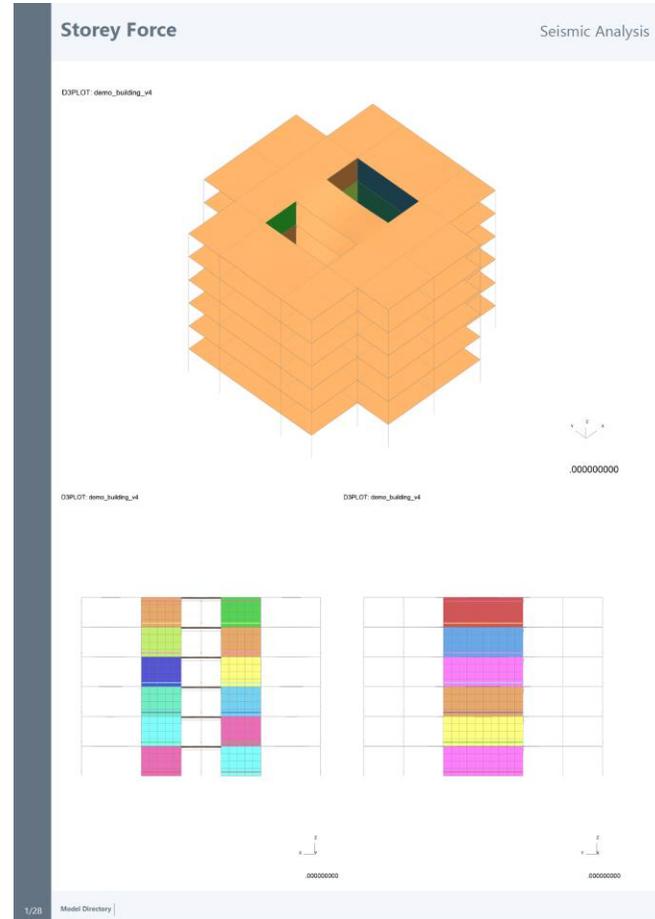
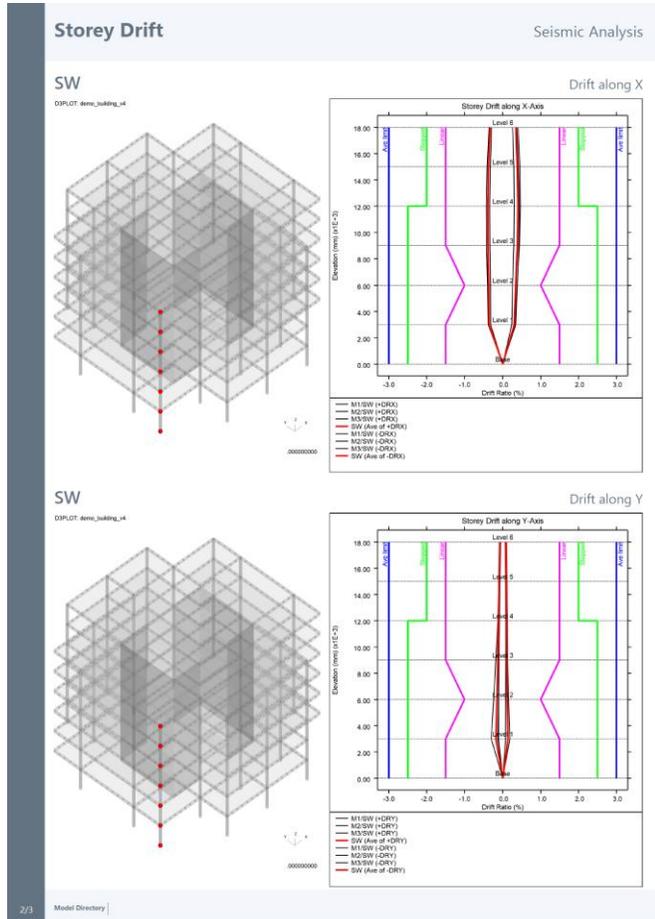
In PRIMER, define DATABASE\_CROSS\_SECTIONS for selected structural members grouped into SET\_PARTs, for each storey.

In T/HIS, storey section forces are extracted for the cross-sections defined.



# Seismic Workflows

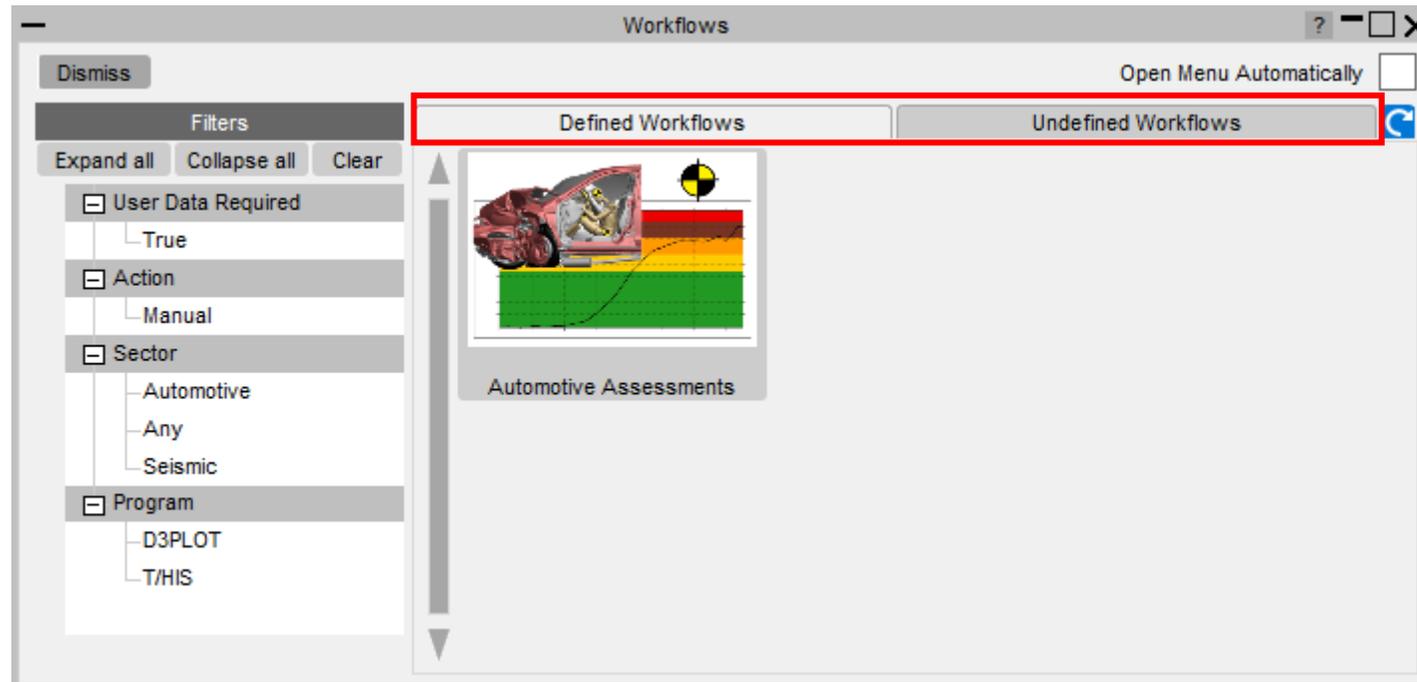
You can also generate automated reports with the REPORTER templates provided:



# Defined and Undefined Workflows

The Workflows menu has been split into two tabs:

- **Defined Workflows** – shows workflows that can be run in T/HIS and have the required data
- **Undefined Workflows** – shows workflows that could be run in T/HIS, but don't have the required data

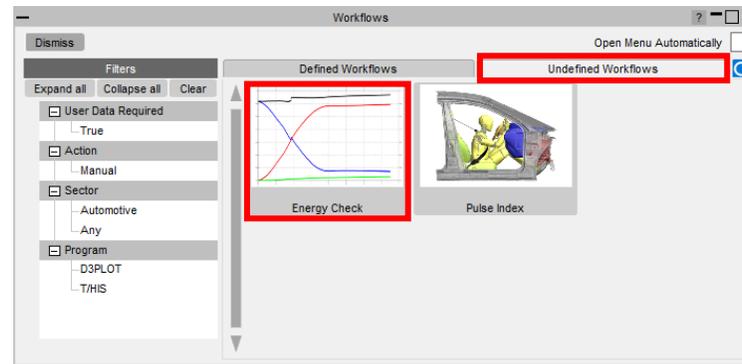


# Defined and Undefined Workflows

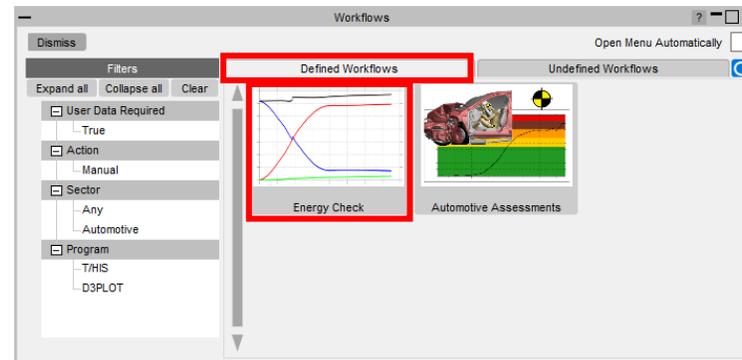
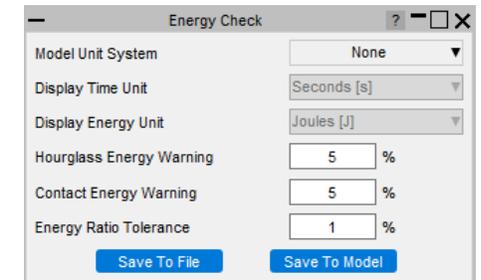
Selecting a workflow in the **Undefined Workflows** tab will open the model in PRIMER and start the workflow to select the required data.

In T/HIS, a window will open telling you to press **Refresh**  when the data has been saved. This will update the Workflows menu, moving the workflow to the **Defined Workflows** tab so it can be run in T/HIS.

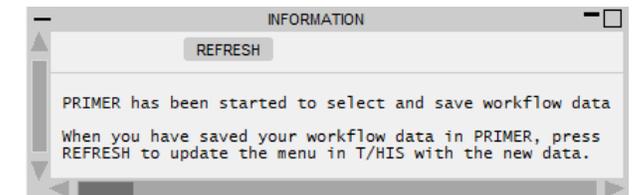
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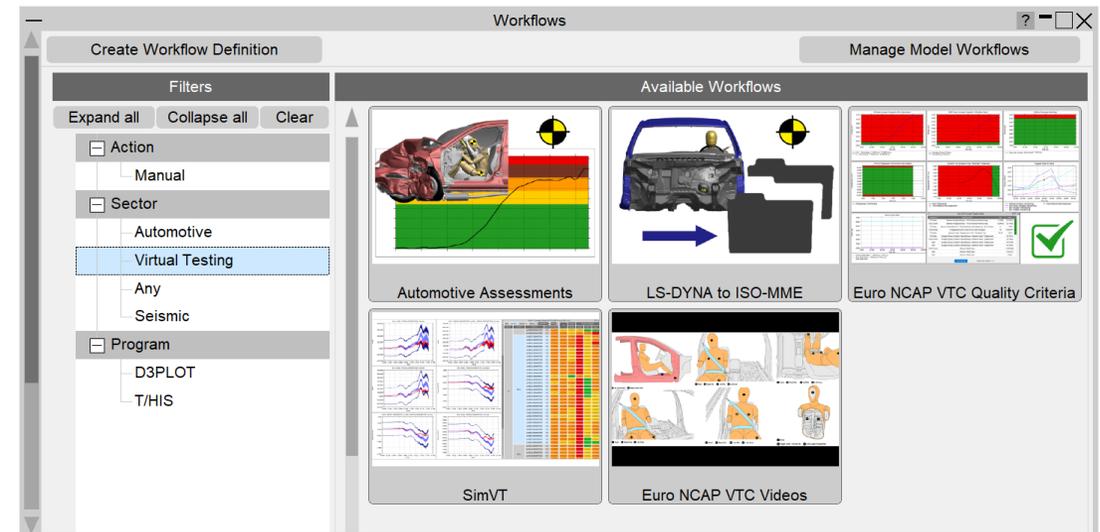
# Virtual Testing

# Virtual Testing

At Oasys Ltd., we are working on software features to support the upcoming Virtual Testing Crashworthiness protocols. The first protocols to be introduced are the [Euro NCAP Virtual Far Side Simulation & Assessment Protocol](#), and [C-NCAP Management Regulation \(2024 Edition\)](#), with others to follow soon.

Oasys 21 contains a set of integrated and complementary Workflow tools to power your Virtual Testing CAE workflows:

- [Automotive Assessments](#) (now supports the Euro NCAP and C-NCAP virtual testing protocols)
- [LS-DYNA to ISO-MME](#)
- [SimVT](#)
- [VTC Quality Criteria](#)
- [VTC Videos](#)



# Virtual Testing

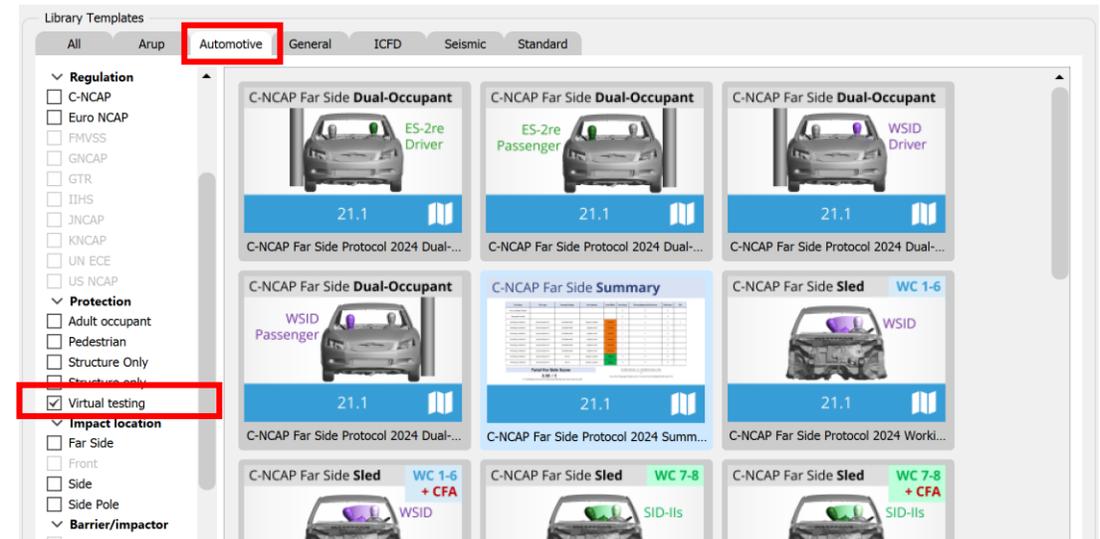
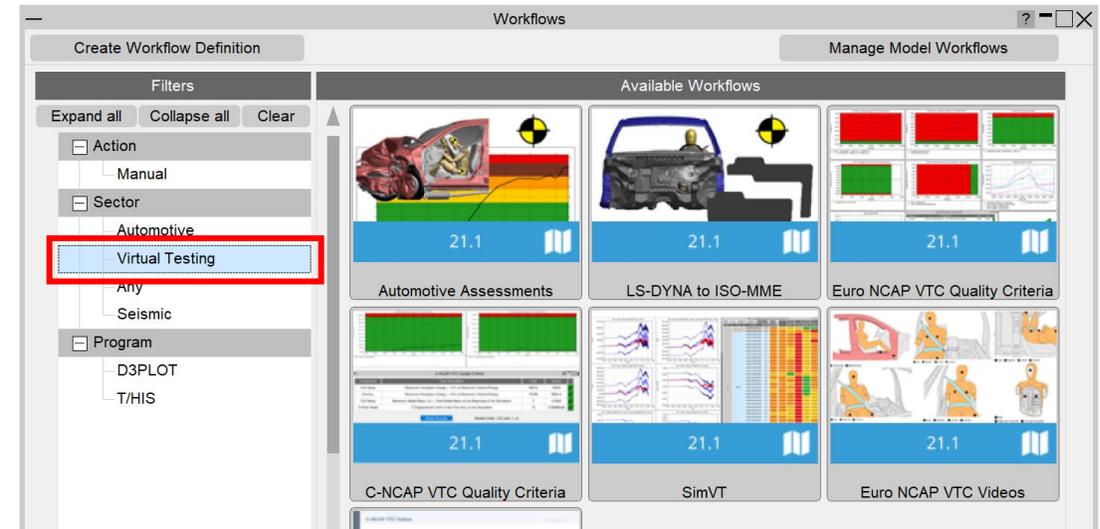
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Virtual Testing presents several challenges for CAE workflows:

- Q1. Good correlation is moving from beneficial to mandatory. As CAE teams, we can no longer rely on conservative assumptions. How do we ensure that physical tests perform as predicted?**
- A1. [SimVT](#) is a powerful new tool for correlation analysis, providing flexibility, and the ability to interrogate correlation results in detail, to help you understand your models' accuracy, robustness, and sensitivity.
- Q2. How do we ensure that the format and quality of information is sufficient when submitting results to Euro NCAP? How to avoid rework and resubmission?**
- A2. Use the [VTC Quality Criteria](#) tools to ensure your models meet the required standard. Use the [VTC Videos](#) tools to provide the video evidence required. Use the [LS-DYNA to ISO-MME](#) tool to export your results data in the required format.
- Q3. CAE teams will need to work more with physical test data, and safety teams will need to work more with simulation. We will also be dealing with more metrics than ever before. How do we improve collaboration and processing?**
- A3. The [LS-DYNA to ISO-MME](#) tool provides seamless transition between simulation and test formats. [SimVT](#) supports test data stored in ISO-MME format as well as a configurable CSV format.
- Q4. How can we manage the large volume of data and processing required for Virtual Testing?**
- A.4 [SimVT](#) helps you summarise the correlation analysis results for all the occupant and structures data channels, as well as providing the ability to sift through the data in more detail. Other tools include REPORTER templates to automate the processing of data. Results tables, graphs and scores can be exported in various formats to link with your team's data management tools and processes.

# Virtual Testing

- All the new Virtual Testing tools can be accessed from the **Tools** → **Workflows** menus in PRIMER, D3PLOT and T/HIS by filtering for **Virtual Testing**.
- REPORTER templates can be found at **File** → **Open Library Template...** by selecting the **Automotive** tab and filtering for **Virtual testing**.



# LS-DYNA to ISO-MME

- “LS-DYNA to ISO-MME” is a new Workflow tool to convert LS-DYNA results into the ISO-MME format specified by the Euro NCAP Virtual Far Side protocol. It can also be used to export the channels required by the C-NCAP Far Side Occupant Protection Protocol.
- [Automotive Assessments](#) workflow user data removes the need to manually map LS-DYNA entities to ISO-MME channel codes.
  1. In **PRIMER**, populate all the fields required by the Euro NCAP or C-NCAP protocol. Contact data and Distance between head CoG and excursion lines can be populated automatically. When you save these, you can reuse the settings for subsequent LS-DYNA runs.
  2. In **T/HIS**, perform the export to ISO-MME format. Solver and simulation information can also be populated automatically.

The screenshot displays the 'LS-DYNA to ISO-MME' software interface, which is divided into several sections for data entry:

- Automotive Assessments User data:** Includes fields for 'Automotive Assessments Crash Test' (Far Side + VTC), 'Automotive Assessments Regulation' (EuroNCAP), and 'Automotive Assessments Version' (2024).
- User data:** Includes fields for 'Test name' (Far side), 'Laboratory name' (Oasys LS-DYNA Environment), 'Customer name' (Euro NCAP), 'Customer test ref number' (001), 'Customer project ref number' (1234), 'Virtual testing ref ID' (FS\_Pole\_75\_x-ref\_z-ref\_50M\_Sim\_1), 'Test date' (30/01/2024), 'ISO-MME format' (1.6), 'Title' (Euro NCAP 2024), 'Regulation' (Far side VTC), 'Type of data source' (Simulation), 'Dummy Simulation Model Specification' (WSID 50M v7.6), 'Reference to Dummy Model Qualification Documentation' (WSID 50M v7.6.pdf), and 'Required output channels CSV' (NCAP\_VTC\_Channels\EuroNCAP\_VTC\_LHD.csv).
- Contact data:** Includes fields for 'Contact Type between dummy and seat' (S2S SOFT0 FS=0.2) and 'Contact Type between dummy and seatbelt' (S2S SOFT1 FS=0.2), with a 'Get contact information' button.
- Vehicle data:** Includes fields for 'Name' (TUG), 'Reference number' (1234), 'Longitudinal velocity' (20), 'Lateral velocity' (12), and 'Mass' (1000).
- Distance between head CoG and excursion lines:** Includes fields for 'Distance between head CoG and green line (in metres)' (0.520), 'Distance between head CoG and yellow line (in metres)' (0.645), 'Distance between head CoG and orange line (in metres)' (0.770), and 'Distance between head CoG and red line (in metres)' (0.8), with a 'Calculate distance' button.

A red box at the bottom right contains the following text: 'Textbox fields with this colour are required for successful LS-DYNA to ISO-MME conversion. Note that all fields are required to conform to the Euro NCAP VTC protocol.'

# LS-DYNA to ISO-MME

- The LS-DYNA to ISO-MME Workflow can be automated using the REPORTER template provided. The report generated contains a summary of the ISO-MME file information and individual channel graphs, as well as highlighting any missing data for correction.

The Reporter output consists of several sections:

### User Data

Description	Value
Test Name	Far side
Laboratory Name	Oasys LS-DYNA Environment
Customer Name	Euro NCAP
Customer Test Reference Number	001
Customer Project Reference Number	1234
Virtual Testing Reference ID	FS_Pole_75_x-ref_z-ref_S0M_Sim_1
Type of Test	SideImpact
ISO-MME Format Version	1.6
Subtype of Test	Far Side + VTC
Regulation	Far side VTC
Test Date	30/01/2024
Title	Euro NCAP 2024
Type of data source	Simulation
Dummy Simulation Model Specification	WSID S0M v7.6
Reference to Dummy Model Qualification Documentation	WSID S0M v7.6.pdf
Distance between head CoG and green line	0.520
Distance between head CoG and yellow line	0.645
Distance between head CoG and orange line	0.770
Distance between head CoG and red line	0.5

### Solver Information

Description	Value
Solver Name	LS-Dyna
Solver Version	ls-dyna_mpp_s_R11_2_2
Solver Precision	SP
Platform Name	Xeon64 System

### Simulation Information

Description	Value
Number of CPUs	32
Time step setting	6.7698e-8 s
Contact Type between dummy and seat	S2S SOFT1 nu=0.2
Contact Type between dummy and seatbelt	S2S SOFT1 nu=0.2
Number of contacts used in the overall simulation setup	39
Number of elements	1796163
Mass of total setup (used for quality checks)	343
Mass of dummy in kg	4
Mass of seat in kg	2
Mass of sled in kg	20
Mass of centre console in kg	2

### Vehicle Data

Description	Value
Name	TUG
Reference number	1234
Longitudinal velocity	20
Lateral velocity	12
Mass	1000

### Channel 88 of 115: Missing user data for 11ARBG000WSFOX0

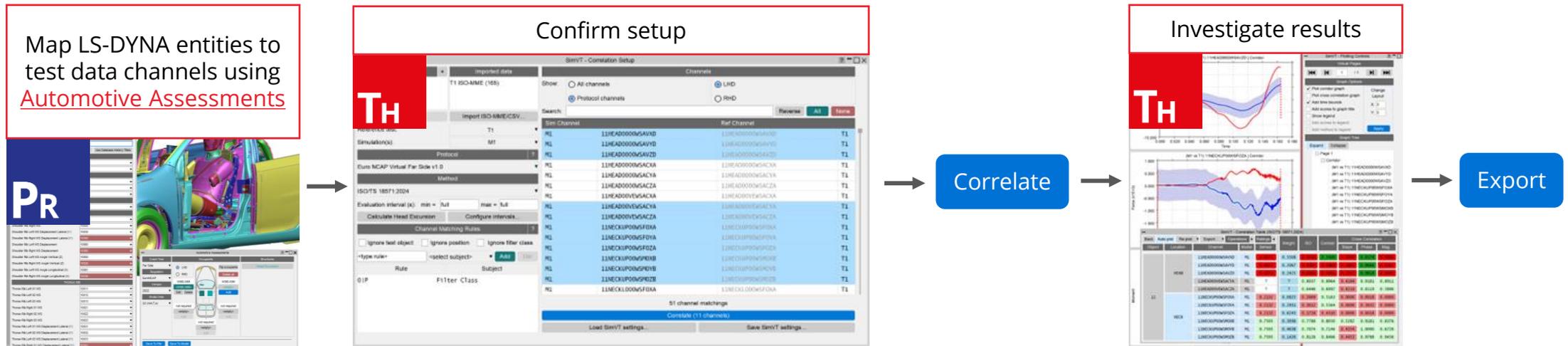
This graph shows a plot of missing user data for channel 11ARBG000WSFOX0. The y-axis ranges from 0.0 to 1.0, and the x-axis ranges from 0.000 to 0.160. The plot shows a flat line at 0.0, indicating no data was recorded for this channel.

### Channel 4 of 115: Dummy Front Left Head WS Angular Velocity Longitudinal (X) Unfiltered

This graph shows the angular velocity for channel 11HEAD000WSAVX0. The y-axis ranges from -5.0 to 35.0, and the x-axis ranges from 0.000 to 0.160. The plot shows a curve that starts at 0.0, rises to a peak of approximately 32.0 at 0.120, and then falls back to 0.0 by 0.140.

# SimVT

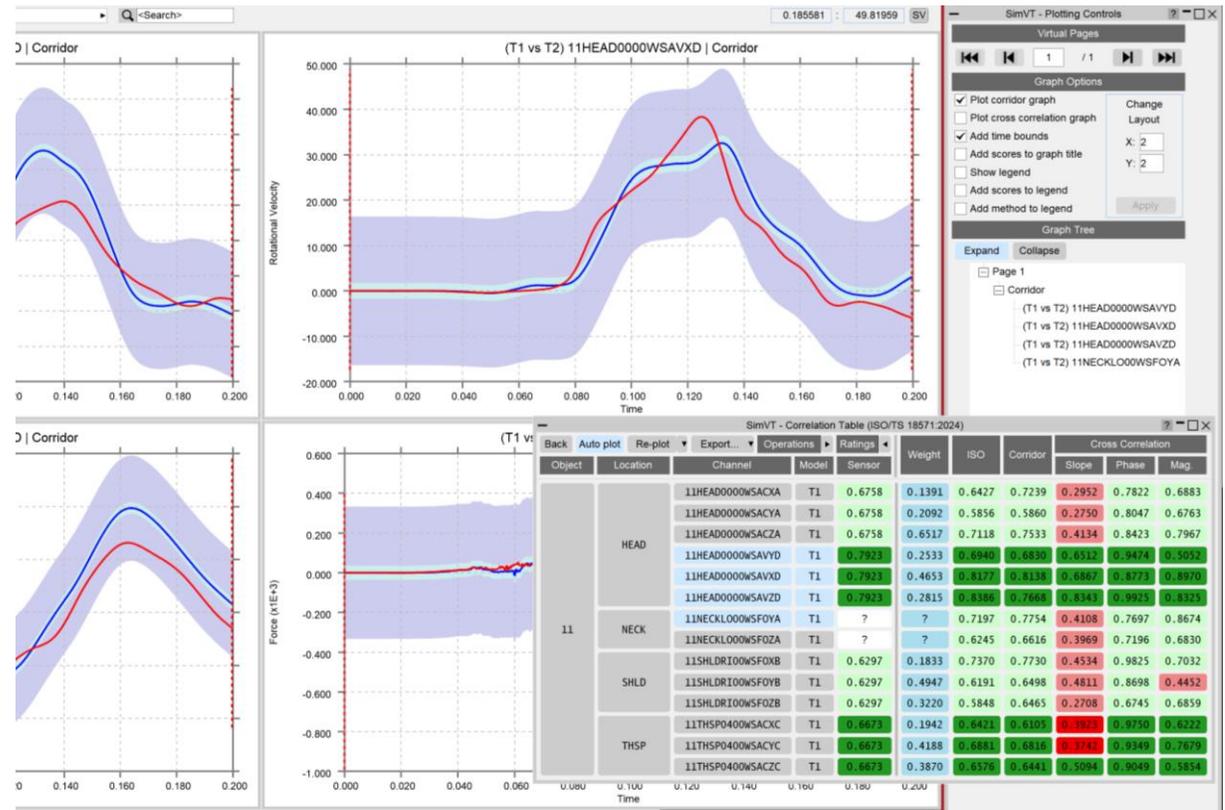
- SimVT is a powerful interactive tool for correlating simulation data vs test, or indeed any combination of: LS-DYNA models, ISO-MME data or CSV data.
- SimVT supports the Euro NCAP and C-NCAP Virtual Testing protocols and can be used to identify sensors that fail to pass Validation Criterion 1 or correlation fitting index requirements.



The SimVT Workflow

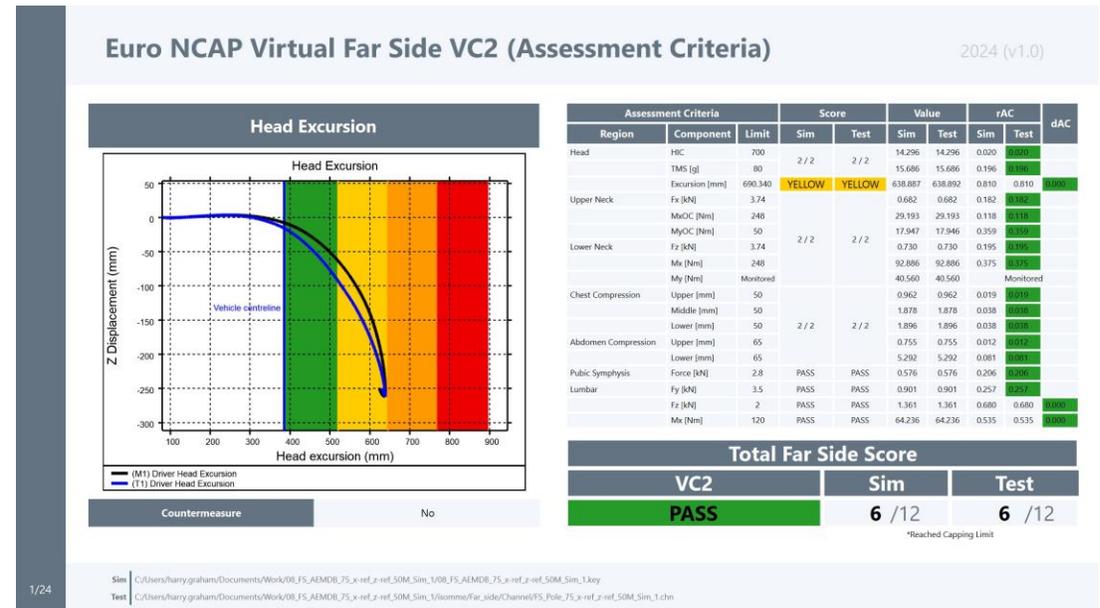
# SimVT

- SimVT seamlessly aligns simulation curves to tests using ISO-MME Channel Codes.
- You can create custom rules for pairing approximate matches.
- Hundreds of correlations are achievable with a single click.
- Results are displayed in a table and can be exported to CSV.
- Graphs of all correlations can be easily plotted and navigated.
- Settings files can be saved to restore previous sessions.



# Euro NCAP Virtual Far Side Validation Criterion 2

- The **Euro NCAP Virtual Far Side 2024 VC2 (Assessment Criteria)** REPORTER Template can be used to perform the Validation Criterion 2 (Assessment Criteria) check according to section 6.3.10 of the Euro NCAP VTC Simulation and Assessment Protocol v1.0.
- Before running the template, you need to set up user data in PRIMER's Automotive Assessments Workflow using the Euro NCAP 'Far Side + VTC' protocol.
- You can also perform [VC2 manually in T/HIS](#).

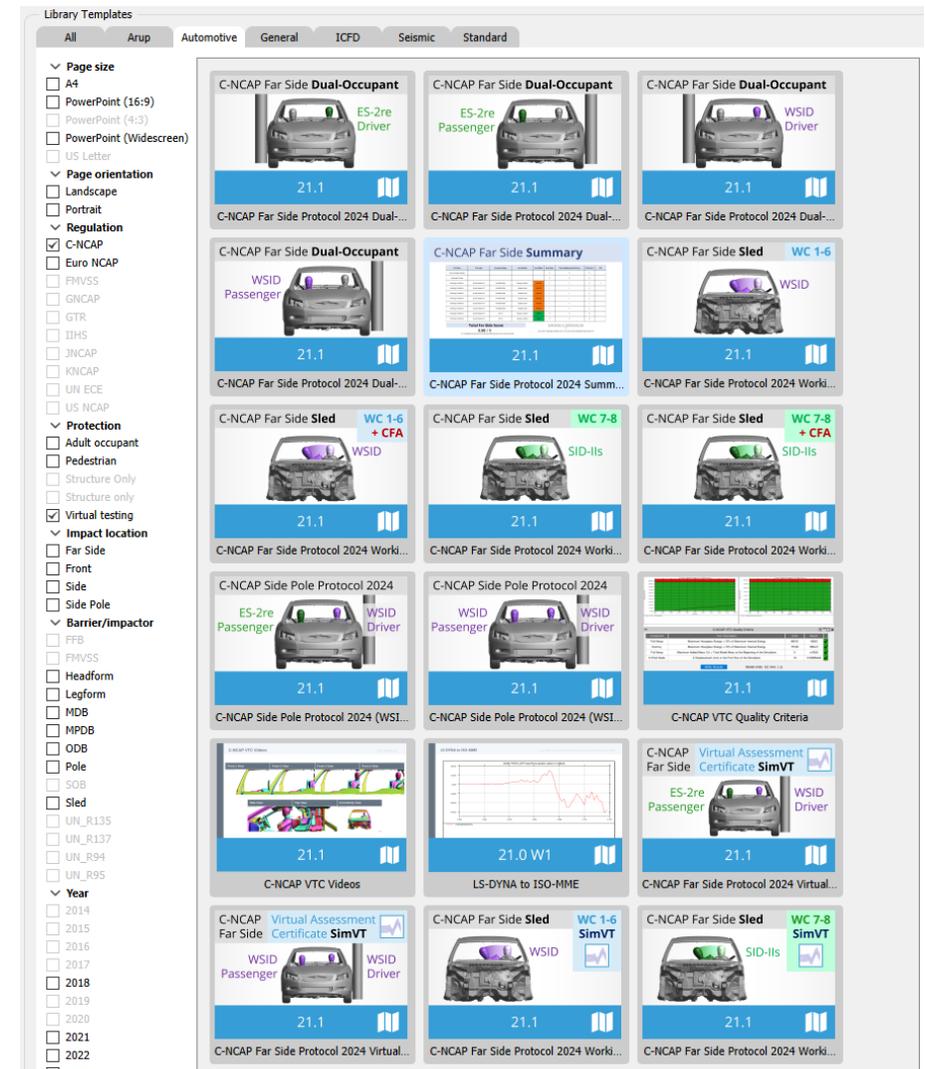


# C-NCAP Management Regulation (2024 Edition)

Oasys 21.1 has new support for the various requirements of the C-NCAP Far Side Occupant Protection Protocol, including:

- For each of the eight Working Conditions:
  - Occupant injury assessment
  - ISO Correlation Fitting indices
  - Correction Factor A
- Dual-Occupant Penalty calculation
- ISO correlation fitting indices for the Virtual Assessment Certificate (prerequisite for the symmetry of far side occupant protection airbags)
- Overall score calculation

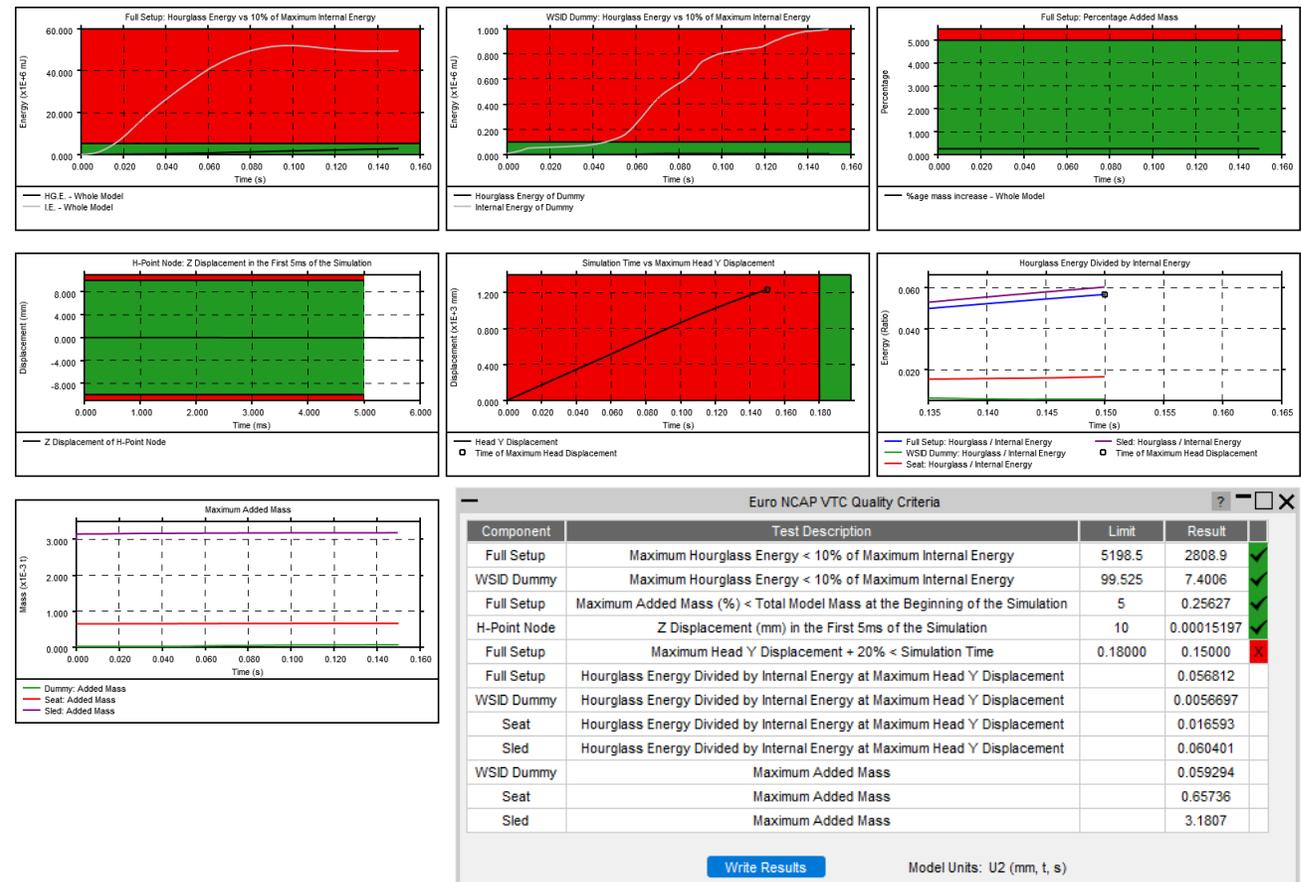
[Read the documentation to learn more](#)



# Euro NCAP VTC Quality Criteria

- “Euro NCAP VTC Quality Criteria” is a new, convenient tool for assessing the quality criteria specified in section 6.1 of the Euro NCAP Virtual Far Side protocol.

1. In **PRIMER**, select the model entities required for the quality checks, and the relevant model and display units. Saved user data can be reused for subsequent LS-DYNA runs.
2. In **T/HIS**, the quality checks are calculated immediately. Graphs illustrate the results of each check. A summary table appears, with the option to write the results to a CSV file.



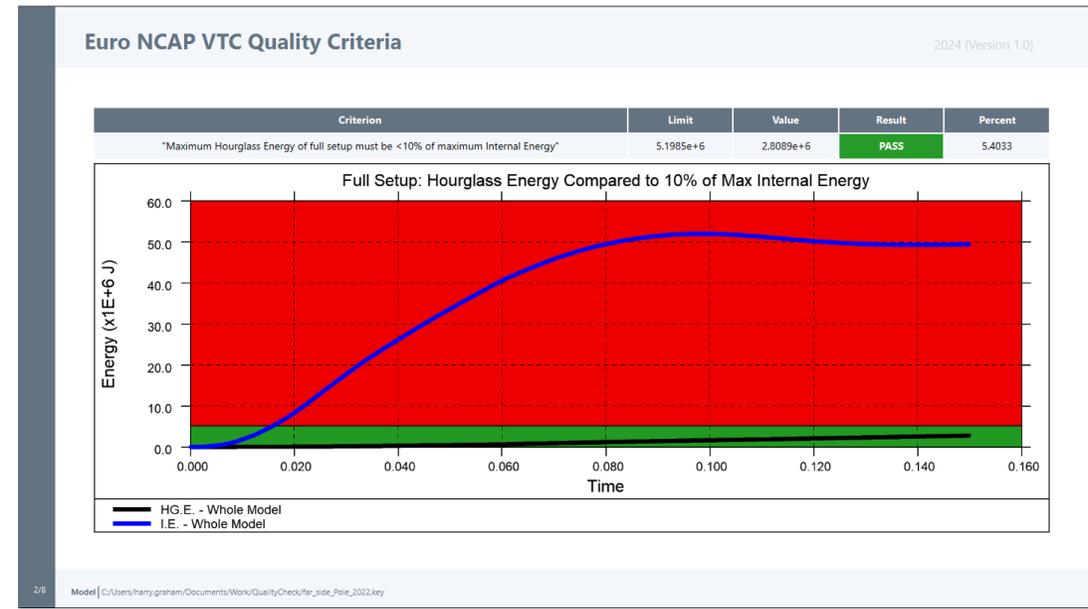
# Euro NCAP VTC Quality Criteria

- The Euro NCAP VTC Quality Criteria Workflow tool can be automated using the REPORTER template provided.

**Euro NCAP VTC Quality Criteria** 2024 (Version 1.0)

Summary				
Component	Test Description	Value	Limit	Result
Full Setup	Maximum Hourglass Energy < 10% of Maximum Internal Energy	2.8089e+6	5.1985e+6	PASS
WSID Dummy	Maximum Hourglass Energy < 10% of Maximum Internal Energy	7400.6	99525	PASS
Full Setup	Maximum Added Mass (%) < Total Model Mass at the beginning of the simulation	0.25627	5	PASS
H-Point Node	Z Displacement (mm) in the first 5 ms of the simulation	70.006	10	FAIL
Full Setup	(Time of Maximum Head Y Displacement) + 20% < Simulation Time	0.15	0.18	FAIL
Full Setup	Hourglass Energy divided by Internal Energy at Time of Maximum Head Y Displacement	0.056812	[monitored]	[monitored]
WSID Dummy	Hourglass Energy divided by Internal Energy at Time of Maximum Head Y Displacement	0.0056697	[monitored]	[monitored]
Seat	Hourglass Energy divided by Internal Energy at Time of Maximum Head Y Displacement	0.016593	[monitored]	[monitored]
Sled	Hourglass Energy divided by Internal Energy at Time of Maximum Head Y Displacement	0.060401	[monitored]	[monitored]
Dummy	Maximum Added Mass	5.9294e-5	[monitored]	[monitored]
Seat	Maximum Added Mass	0.00065736	[monitored]	[monitored]
Sled	Maximum Added Mass	0.0031807	[monitored]	[monitored]

1/8 Model | C:\Users\harry.graham\Documents\Work\QualityCheck\far\_side\_Pole\_2022.key

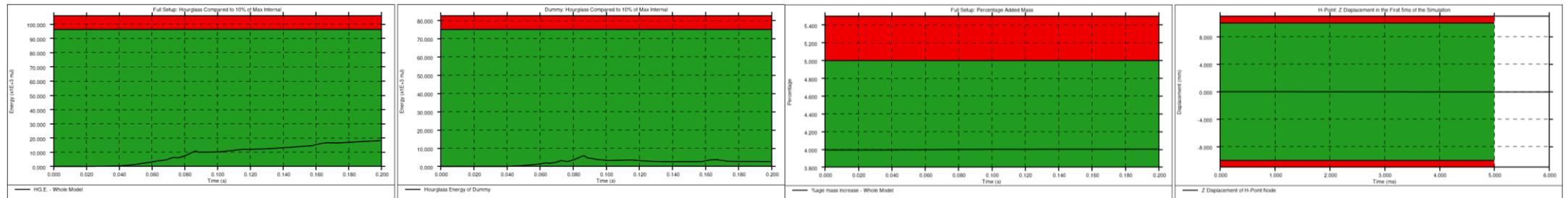


# C-NCAP VTC Quality Criteria

- The C-NCAP VTC Quality Criteria Workflow tool follows the same principals as the Euro NCAP version but assesses the quality criteria specified in section H.1.1(f) of the C-NCAP Far Side Simulation & Assessment Protocol.
- The tool can be automated using the REPORTER template provided.

Component	Test Description	Limit	Result	
Full Setup	Maximum Hourglass Energy < 10% of Maximum Internal Energy	96312	18243	✓
Dummy	Maximum Hourglass Energy < 10% of Maximum Internal Energy	75128	5834.5	✓
Full Setup	Maximum Added Mass (%) < Total Model Mass at the Beginning of the Simulation	5	4.0043	✓
H-Point Node	Z Displacement (mm) in the First 5ms of the Simulation	10	0.00085449	✓

Write Results      Model Units: U2 (mm, t, s)



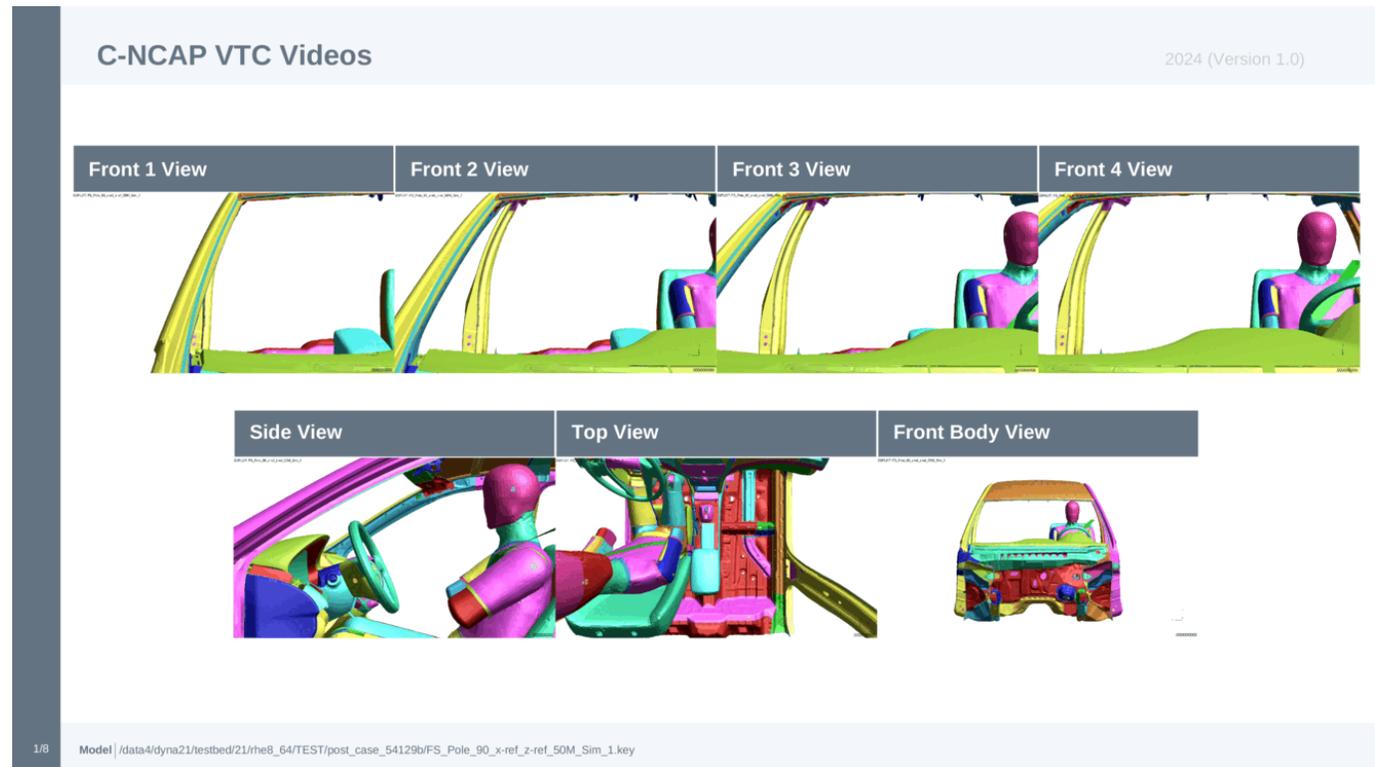
# Euro NCAP VTC Videos

- The **Euro NCAP VTC Videos** Workflow tool helps you calculate the views and export the videos specified in section 5.2.1 of the Euro NCAP Virtual Far Side protocol.
- The tool attempts to calculate the camera positions automatically based on model entities you define in **PRIMER**. You can then adjust and save the views in **D3PLOT** to be reused to capture the videos for future LS-DYNA runs. The whole process can be automated using the **REPORTER** template provided.



# C-NCAP VTC Videos

- The **C-NCAP VTC Videos** Workflow tool follows the same principles as the Euro NCAP version but helps you calculate the views and export the videos specified in section H.2.8 of the C-NCAP Far Side Occupant Protection Protocol (2024 Edition).
- Use the standard Workflow method in **PRIMER** and **D3PLOT** or the whole process can be automated using the **REPORTER** template provided.



# ISO-MME Export

# ISO-MME Export

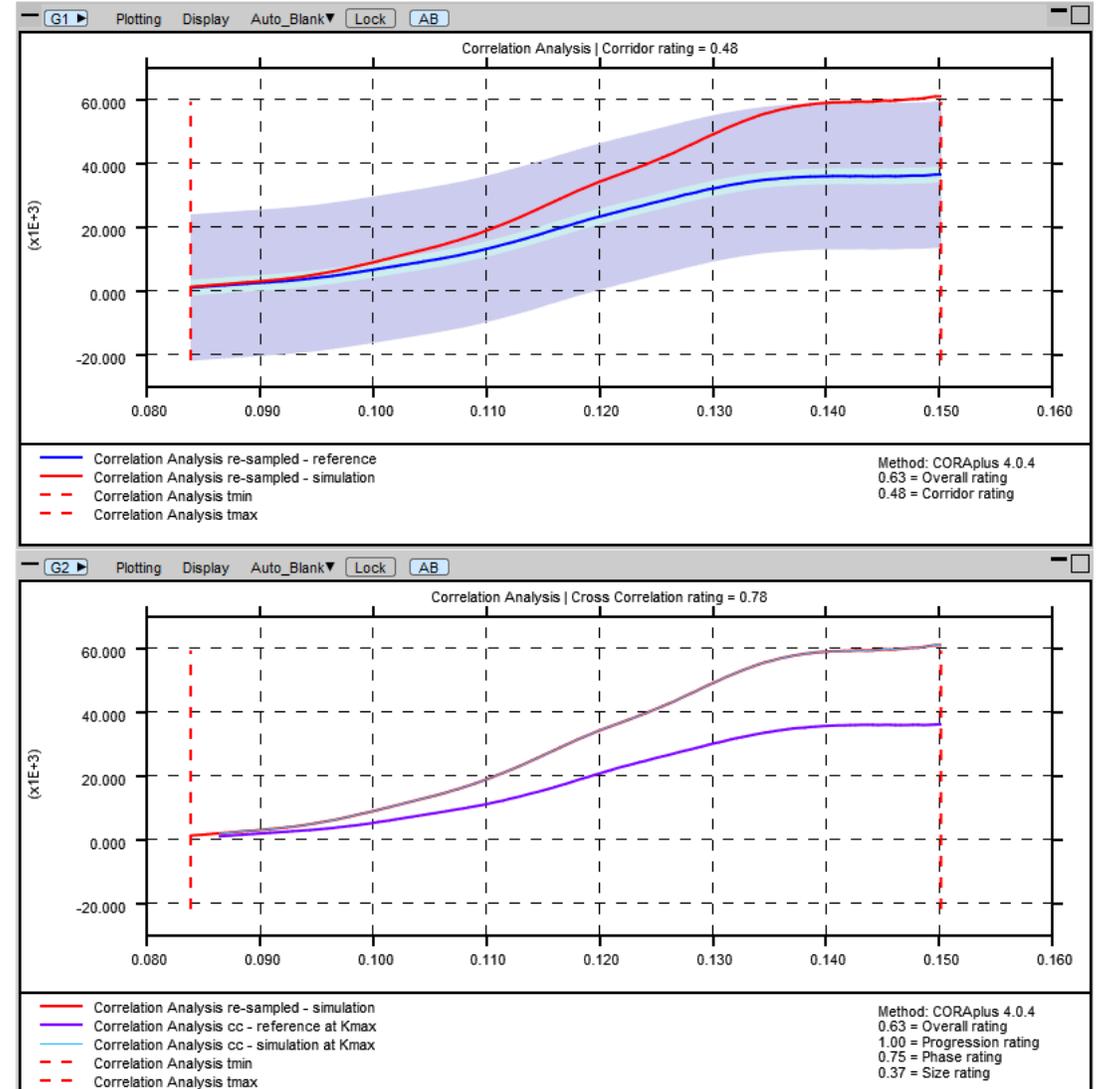
- T/HIS can now read and write both ISO-MME versions 1.6 and 2.0.
- The configuration file structure for exporting ISO-MME Output has been revised to accommodate channels that do not belong to pre-defined objects.
- You can now perform operations on defined channels using the configuration files to export them as separate channel curves.
- Comprehensive information regarding the configuration file changes is available in the T/HIS manual.

```
{
  "thisVersion": "21",
  "thisBuildNumber": "6455",
  "testName": "Far side",
  "timestamp": "22/10/2024, 06:53:10",
  "virtualTestingReferenceId": "FS_Pole_75_x-ref_z-ref_50M_Sim_1",
  "formatVersion": "1.6",
  "unitSystemModel": "U2",
  "unitSystemDisplay": "U1",
  "descriptors": [
    {
      "description": "Title",
      "value": "Euro NCAP 2024",
      "label": "title"
    }
  ],
  "dummies": [
    {
      "testObject": "1",
      "position": "1",
      "vehicleTestObject": "1",
      "name": "PDB WSID 50M 7.6 RHD",
      "gender": "male"
    }
  ],
  "vehicles": [
    {
      "testObject": "1",
      "position": "0",
      "driverPosition": "1",
      "name": "TUG",
      "refNumber": "1234",
      "velocityLateral": 12,
      "velocityLongitudinal": 20,
      "mass": 1000,
      "impactSide": "RI"
    }
  ],
  "channels": [
    {
      "testObject": "1",
      "position": "1",
      "mainLocation": "HEAD",
      "fineLocation1": "00",
      "fineLocation2": "GB",
      "fineLocation3": "WS",
      "physicalDimension": "DC",
      "direction": "X",
      "filter": "0",
      "entityType": "node",
      "component": "coord X",
      "id": 10123,
      "xAxisInterval": 0.0001,
      "iso": true,
      "write": false
    }
  ],
  "operations": [
    {
      "comment": "Converting GB to 00 as that is the expected channel ISO code for VIC protocol",
      "operation": "mul",
      "input": [
        {
          "11HEAD00GBWSDCX0",
          1
        }
      ],
      "output": "11HEAD0000WSDCX0",
      "iso": true,
      "graph": false,
      "write": true
    }
  ]
}
```

# CORA Tool

# CORA Tool Enhancements

- Now supports ISO/TS 18571:2024 method (previously called ISO/TS 18571:Euro NCAPv1.0).
- New plotting features:
  - Corridor graph
  - Cross-correlation graph
- Enhanced graph customisation:
  - Include scores in legend and titles
  - Add method descriptions to legend



# Per-Monitor DPI Awareness

(Windows platforms only)

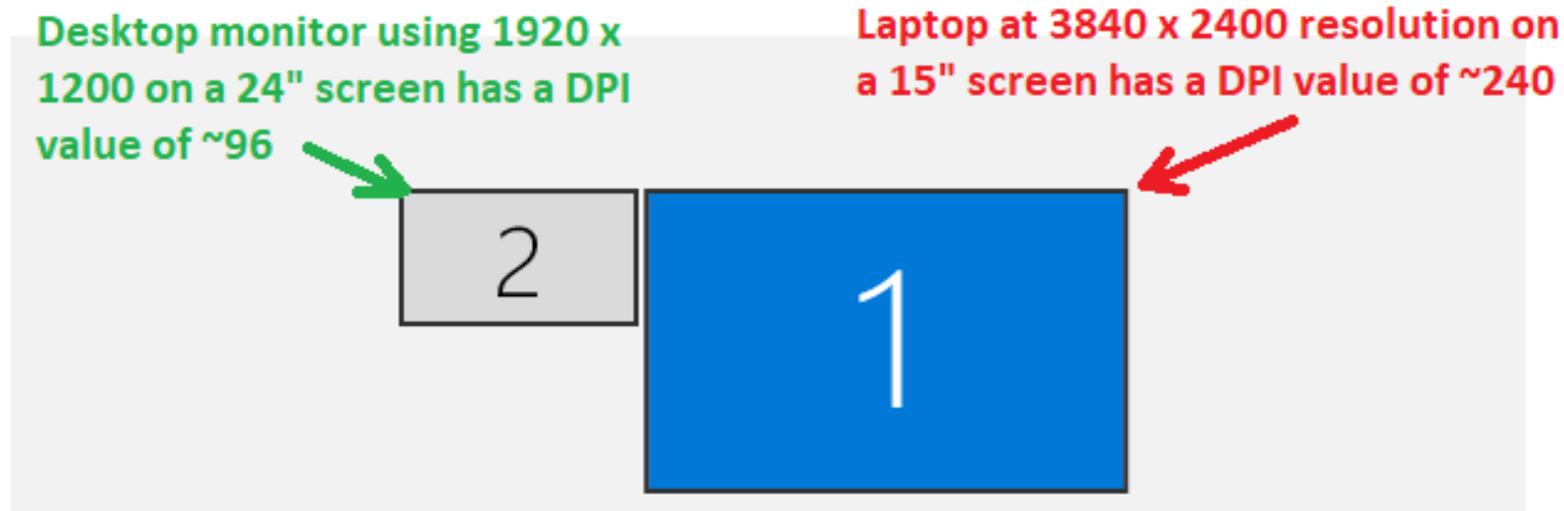
# Per-Monitor DPI Awareness

---

Windows 10 allows monitors of different resolutions to be used on a single desktop. For example, when a high-resolution laptop is attached to a lower-resolution monitor, you will see something like this in Windows “Display Settings”:

## Rearrange your displays

Select a display below to change the settings for it. Press and hold (or select) a display, then drag to rearrange it.



# Per-Monitor DPI Awareness

---

When the monitors have very different Dots Per Inch (DPI) values, windows will look either “too big” or “too small” when moved to a different monitor unless the application adjusts its fonts and other scaling. This was a problem with Oasys software before Oasys 21.

From Oasys 21 onwards, Oasys applications will detect when they are moved to a different monitor and will resize themselves and their contents to fit correctly. Specifically:

- The master application window will resize
- Fonts will resize
- Line widths and spacing in the user interface will resize

The appearance may not be identical, since fonts scale in integer steps of point size, but it should be close. Bear in mind that images are captured at the resolution of the monitor so consider this when creating images.

# REPORTER Variables

# Default names for REPORTER variables

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- Before Oasys 21, REPORTER default variable names were prefixed with ITEM\_ $n$ , where  $n$  was the number of the item on the page in the T/HIS item tree. Because items in the T/HIS item tree are numbered from 1 on each page, it was common to have the same prefix for default variable names on multiple pages and therefore to have identical default variable names for items on multiple pages, resulting in variables being overwritten in REPORTER.
- In Oasys 21, default variable names are prefixed with the REPORTER item name, which defaults to a format like “this6”, “this6\_1” for T/HIS items. Since item names in REPORTER are unique, this ensures default variable names generated in T/HIS are also unique.

# JavaScript API

# JavaScript API: Behaviour of scripts using windows

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- The way that scripts that use windows/GUIs are run has changed in version 21.
- All programs that have a graphical user interface (GUI) use an “event loop” to process any mouse/keyboard events.  
T/HIS has a main “event loop” to process all of the program’s events.
- In version 20 and before, if a script created and showed a window, T/HIS would start a new “event loop” to manage and process that JavaScript window.
- The script would not return from the window Show() call until the window was hidden/closed.  
i.e. showing the window would “block” execution of the script until the window was closed.
- When the window is closed, the script continues.
- When execution reaches the end of the script, the script is terminated.

# JavaScript API: Behaviour of scripts using windows

---

- For example, in version 20 and earlier, in the following script, “Hello, world!” will not be printed until the window is closed because the call to `w.Show()` will not return until the window is closed.

```
// Create a window with a widget
var w = new Window("Test", 0.5, 0.6, 0.5, 0.6);
var l = new Widget(w, Widget.LABEL, 0, 50, 0, 6, "Press X to close the window");

// Show the window and start event loop
w.Show();

// Print message
Message("Hello, world!");
```

- When the window is closed the message is printed and the script will then terminate as execution has reached the end of the script.

# JavaScript API: Behaviour of scripts using windows

---

- In version 21 the behaviour has changed.
- If a script creates and shows a window, T/HIS will **\*not\*** start a new “event loop” to manage and process that JavaScript window.
- The window will now be processed from the main “event loop” in T/HIS .
- The script now returns from the window Show() as soon as the window is shown, and execution of the script continues.  
i.e. showing the window no longer “blocks” execution of the script until the window is closed.
- When execution reaches the end of the script, the script is **\*not\*** terminated.
- The script continues running “in the background” as the script has shown a window.

# JavaScript API: Behaviour of scripts using windows

---

- For example, in version 21, in the following script “Hello, world!” will be printed immediately after the window is shown, because the call to `w.Show()` returns after the window is shown.

```
// Create a window with a widget
var w = new Window("Test", 0.5, 0.6, 0.5, 0.6);
var l = new Widget(w, Widget.LABEL, 0, 50, 0, 6, "Press X to close the window");

// Show the window
w.Show();

// Print message
Message("Hello, world!");
```

- When the message is printed, the script will **\*not\*** terminate when execution reaches the end of the script. The script will continue to run “in the background”

# JavaScript API: Behaviour of scripts using windows

---

- If a script that shows windows continues running “in the background”, and does not terminate when execution reaches the end of the script, how/when does the script terminate?
- A script that uses windows **\*must\*** now call `Exit` to terminate the script.

```
// Create a window with a widget
var w = new Window("Test", 0.5, 0.6, 0.5, 0.6);
var l = new Widget(w, Widget.LABEL, 0, 50, 0, 6, "Press X to close the window");

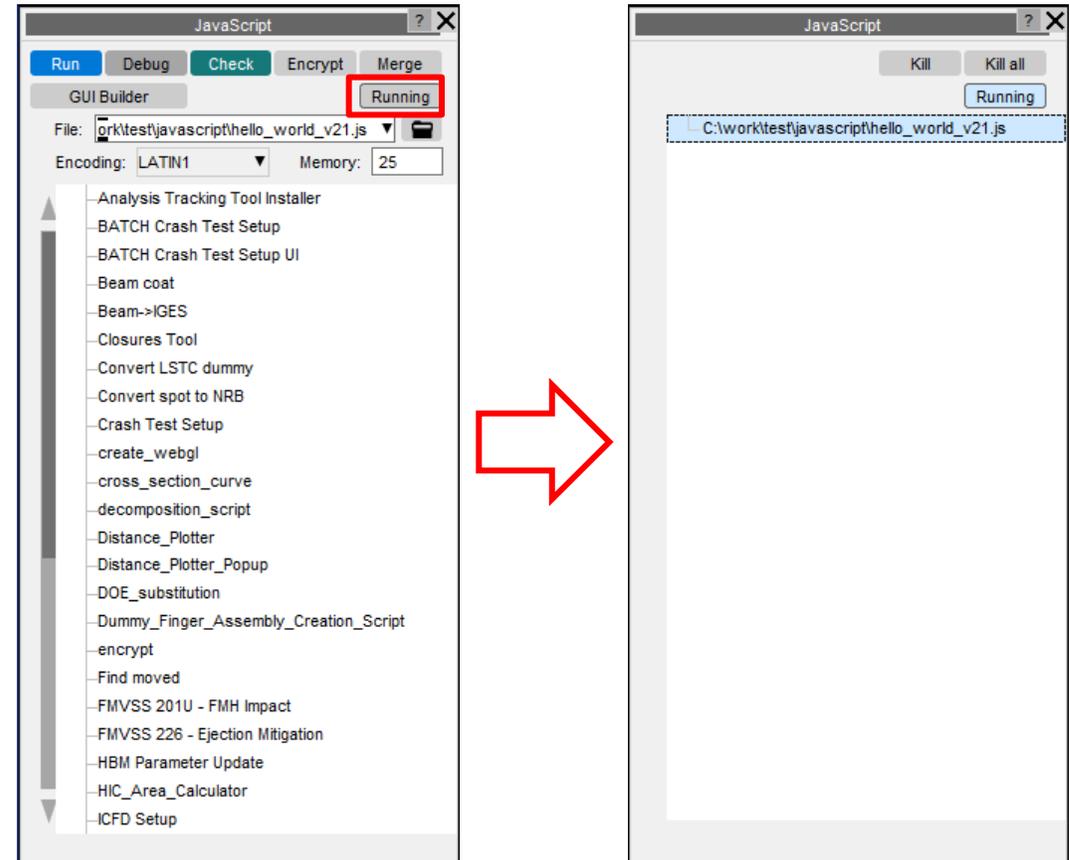
// Exit when window closed
w.onClose = Exit;

// Show the window
w.Show();

// Print message
Message("Hello, world!");
```

# JavaScript API: Behaviour of scripts using windows

- To find what scripts are currently running there is a new “Running” tool in the JavaScript window.
- Any scripts that are currently running will be shown and can be terminated if required.



# JavaScript API

---

New methods added to the Workflow class:

- WriteToFile() – writes a workflow to a JSON file
- WorkflowDefinitionFilename() – returns the workflow definition filename
- Refresh() – scans for fresh workflow data
- ModelUserDataProgramFromIndex() – returns the name of the program that the user data was written from
- ModelUserDataVersionFromIndex() – returns the version of the program that the user data was written from
- ModelUserDataBuildFromIndex() – returns the build number of the program that the user data was written from

# JavaScript API

---

An extra optional argument has been added to `Workflow.WorkflowDefinitionFilename()`

- If defined it returns the filename of the workflow definition filename for the specified window
- If not defined it returns the workflow definition filename for the workflow selected by the user in the workflows menu

An extra optional argument has been added to `Workflow.NumberOfSelectedModels()`

- If defined it returns the number of models that have data for the specified workflow (out of the models that were selected by the user in the workflows menu).
- If not defined it works as before where it returns the number of models that were selected by the user in the workflows menu.

# JavaScript API

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An extra optional argument has been added to `Workflow.ModelIdFromIndex()`

- If defined it looks through the list of models that have data for the named workflow out of the models selected by the user and returns the model id of the model at the specified index in the list
- If not defined it works as before where it returns the model id of the model at the specified index in the list of models that were selected by the user

An extra optional argument has been added to `Workflow.ModelUnitSystemFromIndex()`

- If defined it looks through the list of models that have data for the named workflow out of the models selected by the user and returns the unit system of the model at the specified index in the list
- If not defined it works as before where it returns the unit system of the model at the specified index in the list of models that were selected by the user

# JavaScript API

---

- An onHide event has been added to the Window class
- New method Build() added in Utils class to return T/HIS build number

# Preferences

# New Preferences

Preference	Description
<b>oasys*workflow_only_use_specified_directory</b>	Only scan location set by preference oasys*workflow_definitions_directory for Workflow definitions.
<b>oasys*workflow_user_data_directory</b>	Name of a folder to search in for workflow user data
<b>oasys*workflow_max_upward_folder_search_depth</b>	Maximum number of folders to search up to look for workflow user data
<b>oasys*initial_view_orientation</b>	Initial view orientation for the graphics window
<b>this*file_buffer_size</b>	File buffer size used for read THF (d3thdt) files
<b>this*line_scale_dpi</b>	Scale lines according to display DPI resolution

# Contact Information

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